

## Hillary vs. Bernie

```
[1]: import cvxpy as cp
import numpy as np
import scipy
mat = scipy.io.loadmat('Hillary_vs_Bernie.mat')
X = mat['features_train']
y = mat['labels_train']
m,n = X.shape
Y = np.zeros((m,m),float)
for i in range(m):
    Y[i][i] = y[i][0]
```

**Fitting the model for  $\gamma \in \{0.1, 1, 10\}$**

The optimization problem

$$\begin{aligned} \min_{a,b,\eta} \quad & \|a\| + \gamma \|\eta\|_1 \\ \text{s.t.} \quad & y_i(a^\top x_i - b) \geq 1 - \eta_i \quad \forall i = 1, \dots, m \\ & \eta \geq 0 \end{aligned}$$

to build a linear classifier. Corresponding to the three cases  $\text{gamma1} = 0.1$ ,  $\text{gamma2} = 1$ ,  $\text{gamma3} = 10$ , the optimal solutions are labelled as  $(\mathbf{a1}, \mathbf{b1}, \mathbf{eta1})$ ,  $(\mathbf{a2}, \mathbf{b2}, \mathbf{eta2})$ ,  $(\mathbf{a3}, \mathbf{b3}, \mathbf{eta3})$  respectively.

Here's how we deal with the linear separator on the given data. I formed a matrix  $(Y_{\text{train}} =) Y = \text{diag}(y_1, \dots, y_m)$ . The rows of  $(X_{\text{train}} =) X$  are the vectors  $x_i^\top$ . So  $Xa - \mathbf{b1}$  already gives the evaluation of the linear form on these data points  $\{x_i\}$ . We want to weigh each  $x_i^\top a - b$  with  $y_i$ : this is achieved by taking  $Y(Xa - \mathbf{b1})$  which gives a vector with  $i^{\text{th}}$  entry being  $y_i(x_i^\top a - b)$ .

```
[2]: gamma1 = 0.1
a1 = cp.Variable(n, 'a1')
b1 = cp.Variable(1, 'b1')
eta1 = cp.Variable(m, 'eta1')
obj1 = cp.norm(a1) + gamma1 * (cp.norm(eta1,1))
cons1 = [Y@(X@a1-b1) + eta1 >= 1, eta1 >= 0]
problem1 = cp.Problem(cp.Minimize(obj1), cons1)
print(problem1.solve(verbose = True, solver = cp.ECOS))
print("\nOptimal a: ", a1.value, "\nOptimal b:", b1.value)
```

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CVXPY

v1.4.2

```
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(CVXPY) Mar 20 09:52:49 AM: Your problem has 181 variables, 2 constraints, and 0  
parameters.
```

```
(CVXPY) Mar 20 09:52:49 AM: It is compliant with the following grammars: DCP,  
DQCP
```

```
(CVXPY) Mar 20 09:52:49 AM: (If you need to solve this problem multiple times,  
but with different data, consider using parameters.)
```

```
(CVXPY) Mar 20 09:52:49 AM: CVXPY will first compile your problem; then, it will  
invoke a numerical solver to obtain a solution.
```

```
(CVXPY) Mar 20 09:52:49 AM: Your problem is compiled with the CPP  
canonicalization backend.
```

```
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Compilation
```

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(CVXPY) Mar 20 09:52:49 AM: Compiling problem (target solver=ECOS).
```

```
(CVXPY) Mar 20 09:52:49 AM: Reduction chain: Dcp2Cone -> CvxAttr2Constr ->  
ConeMatrixStuffing -> ECOS
```

```
(CVXPY) Mar 20 09:52:49 AM: Applying reduction Dcp2Cone
```

```
(CVXPY) Mar 20 09:52:49 AM: Applying reduction CvxAttr2Constr
```

```
(CVXPY) Mar 20 09:52:49 AM: Applying reduction ConeMatrixStuffing
```

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(CVXPY) Mar 20 09:52:49 AM: Applying reduction ECOS
```

```
(CVXPY) Mar 20 09:52:49 AM: Finished problem compilation (took 1.305e-02  
seconds).
```

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Numerical solver
```

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(CVXPY) Mar 20 09:52:49 AM: Invoking solver ECOS to obtain a solution.
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Summary
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(CVXPY) Mar 20 09:52:49 AM: Problem status: optimal
```

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(CVXPY) Mar 20 09:52:49 AM: Optimal value: 1.057e+01
```

```
(CVXPY) Mar 20 09:52:49 AM: Compilation took 1.305e-02 seconds
```

```
(CVXPY) Mar 20 09:52:49 AM: Solver (including time spent in interface) took  
4.034e-03 seconds
```

```
10.57269665702442
```

```
Optimal a: [ 0.14105247  0.18277618 -0.73224986 -0.10977297  0.38083898]
```

```
Optimal b: [-3.14700164]
```

```
[3]: gamma2 = 1  
a2 = cp.Variable(n, 'a2')  
b2 = cp.Variable(1, 'b2')  
eta2 = cp.Variable(m, 'eta2')  
obj2 = cp.norm(a2) + gamma2 * (cp.norm(eta2,1))  
cons2 = [Y@(X@a2-b2) + eta2 >= 1, eta2 >= 0]
```

```
problem2 = cp.Problem(cp.Minimize(obj2), cons2)
print(problem2.solve(verbose = True, solver = cp.ECOS))
print("\nOptimal a: ", a2.value, "\nOptimal b:", b2.value)
```

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CVXPY  
v1.4.2

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(CVXPY) Mar 20 09:52:49 AM: Your problem has 181 variables, 2 constraints, and 0 parameters.

(CVXPY) Mar 20 09:52:49 AM: It is compliant with the following grammars: DCP, DQCP

(CVXPY) Mar 20 09:52:49 AM: (If you need to solve this problem multiple times, but with different data, consider using parameters.)

(CVXPY) Mar 20 09:52:49 AM: CVXPY will first compile your problem; then, it will invoke a numerical solver to obtain a solution.

(CVXPY) Mar 20 09:52:49 AM: Your problem is compiled with the CPP canonicalization backend.

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#### Compilation

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(CVXPY) Mar 20 09:52:49 AM: Compiling problem (target solver=ECOS).

(CVXPY) Mar 20 09:52:49 AM: Reduction chain: Dcp2Cone -> CvxAttr2Constr -> ConeMatrixStuffing -> ECOS

(CVXPY) Mar 20 09:52:49 AM: Applying reduction Dcp2Cone

(CVXPY) Mar 20 09:52:49 AM: Applying reduction CvxAttr2Constr

(CVXPY) Mar 20 09:52:49 AM: Applying reduction ConeMatrixStuffing

(CVXPY) Mar 20 09:52:49 AM: Applying reduction ECOS

(CVXPY) Mar 20 09:52:49 AM: Finished problem compilation (took 9.276e-03 seconds).

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#### Numerical solver

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(CVXPY) Mar 20 09:52:49 AM: Invoking solver ECOS to obtain a solution.

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#### Summary

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(CVXPY) Mar 20 09:52:49 AM: Problem status: optimal

(CVXPY) Mar 20 09:52:49 AM: Optimal value: 8.944e+01

(CVXPY) Mar 20 09:52:49 AM: Compilation took 9.276e-03 seconds

(CVXPY) Mar 20 09:52:49 AM: Solver (including time spent in interface) took 3.277e-03 seconds

89.43653660717314

Optimal a: [ 0.20864823 -0.97870147 -1.62007281 -0.4604091 3.76855067]

Optimal b: [-9.24105061]

```
[4]: gamma3 = 10
a3 = cp.Variable(n, 'a3')
b3 = cp.Variable(1, 'b3')
eta3 = cp.Variable(m, 'eta3')
obj3 = cp.norm(a3) + gamma3 * (cp.norm(eta3,1))
cons3 = [Y@(X@a3-b3) + eta3 >= 1, eta3 >= 0]
problem3 = cp.Problem(cp.Minimize(obj3), cons3)
print(problem3.solve(verbose = True, solver = cp.ECOS))
print("\nOptimal a: ", a3.value, "\nOptimal b:", b3.value)
```

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CVXPY
v1.4.2
```

```
=====
(CVXPY) Mar 20 09:52:49 AM: Your problem has 181 variables, 2 constraints, and 0
parameters.
(CVXPY) Mar 20 09:52:49 AM: It is compliant with the following grammars: DCP,
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(CVXPY) Mar 20 09:52:49 AM: Your problem is compiled with the CPP
canonicalization backend.
```

```
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Compilation
```

```
-----
(CVXPY) Mar 20 09:52:49 AM: Compiling problem (target solver=ECOS).
(CVXPY) Mar 20 09:52:49 AM: Reduction chain: Dcp2Cone -> CvxAttr2Constr ->
ConeMatrixStuffing -> ECOS
(CVXPY) Mar 20 09:52:49 AM: Applying reduction Dcp2Cone
(CVXPY) Mar 20 09:52:49 AM: Applying reduction CvxAttr2Constr
(CVXPY) Mar 20 09:52:49 AM: Applying reduction ConeMatrixStuffing
(CVXPY) Mar 20 09:52:49 AM: Applying reduction ECOS
(CVXPY) Mar 20 09:52:49 AM: Finished problem compilation (took 1.229e-02
seconds).
```

```
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Numerical solver
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(CVXPY) Mar 20 09:52:49 AM: Invoking solver ECOS to obtain a solution.
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```

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Summary
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(CVXPY) Mar 20 09:52:49 AM: Problem status: optimal
(CVXPY) Mar 20 09:52:49 AM: Optimal value: 8.524e+02
(CVXPY) Mar 20 09:52:49 AM: Compilation took 1.229e-02 seconds
(CVXPY) Mar 20 09:52:49 AM: Solver (including time spent in interface) took
3.183e-03 seconds
```

852.4305773711759

Optimal a: [ 0.15062914 -0.91314802 -1.52389243 -0.4642144 4.82133807]

Optimal b: [-8.80471718]

## Predicting

First we load the test data. As above, we make a matrix  $Y_{\text{test}}$ .

```
[5]: Xtest = mat['features_test']
      ytest = mat['labels_test']
      mtest, ntest = Xtest.shape
      Ytest = np.zeros((mtest,mtest),float)
      for i in range(mtest):
          Ytest[i][i] = ytest[i][0]
```

We only need to find which side of the hyperplane  $\{x \mid x^T a = b\}$  the test data points are - this is obtained by checking whether  $y_j = \text{sgn}(x_j^T a - b)$ , or equivalently,  $y_j \cdot (x_j^T a - b) > 0$ . So again we consider the vector  $Y_{\text{test}}(X_{\text{test}}a - b\mathbf{1})$  and find out how many of them have non-positive entries - the lower this number, the better is the prediction.

```
[6]: print(sum(Ytest@(Xtest@a1.value-b1.value)<=0))
      print(sum(Ytest@(Xtest@a2.value-b2.value)<=0))
      print(sum(Ytest@(Xtest@a3.value-b3.value)<=0))
```

1  
2  
2

```
[7]: a1.value
```

```
[7]: array([ 0.14105247,  0.18277618, -0.73224986, -0.10977297,  0.38083898])
```